



On hypersurfaces of HGF - Manifold

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Abstract

In previous papers and we have studied some properties of hypersurfaces of HGF-manifold. In this paper I have defined hyperbolic almost Kahler manifold and studied its hypersurface. It has been found that the hypersurface of a hyperbolic almost Kahler manifold is locally quasi-Sasakian manifold. Some results regarding the hypersurfaces of a flat HGF-manifold have also been obtained.

Keywords: HGF-manifold, Hypersurfaces, Geometric structures on manifolds

Introduction

Consider a differentiable manifold M_n of class C^∞ . Let there be a vector valued linear function F of class C^∞ , satisfying the algebraic equation.

$$(1.1) F^2 = -a^2 I_n,$$

Where 'a' is a complex number.

Then F is said to give to M_n a hyperbolic differentiable structure, briefly HGF-structure, defined by algebraic equation (1.1) and the manifold M_n is called HGF manifold [5]. The equation (1.1) gives different algebraic structures for different values of a . If $a \neq 0$, it is a hyperbolic π - structure. $a = \pm 1$, it is an almost complex or an almost hyperbolic product structure. $a = \pm i$, it is an almost product or an almost hyperbolic product structure and $a = 0$, it is an almost tangent structure. in the second case n has to be even and in the second and third case $a^4 = 1$.

If the HGF-structure is endowed with a Hermite metric G .s.t.

$$(1.2) G(F\lambda, F\mu) = G(\lambda, \mu)$$

Then $\{F, G\}$ is said to give to M_n hyperbolic Hermite structure c briefly known as HH-structure subordinate to HGF structure.

In a hyperbolic H-structure, if

$$(1.3) (E \wedge F)(\mu) = 0, \text{ or } (E \wedge F)(F \mu) = 0,$$

is satisfied, then M_n is said to be a hyperbolic Kahler manifolds, F is the Riemannian connexion.

In a hyperbolic H-structure, if

$$(1.4) (E \wedge F)(\mu) + (E \wedge F)(\lambda) = 0,$$

is satisfied, then M_n is said to be hyperbolic nearly Kahler manifold. Let us consider M_n and M_m as the HH - manifold and its hypersurface respectively.

Let $b : M_m \rightarrow M_n$ be the embedding map, s.t. $p \in M_m \rightarrow bp \in M_n$.

Let B be the corresponding Jacobian map, s.t. a vector field X in M_m at p BX in M_n at bp . Let g be the induced Riemannian metric in M_m . Thus we have-

$$(1.5) G(BX, BY) = g(X, Y),$$

for arbitrary vector fields X, Y in M_m .

$$(1.6) a) G(N, N) = 1,$$

$$(1.6) b) G(N, BX) = 0,$$

for a unit normal to M_m .

If we put

$$(1.7) a) FBX = B(fX) + u(X)N,$$

$$(1.7) b) FN = -BU.$$

Then it can be easily seen that

$$(1.8) a) \bar{x} = -a^2 X + u(X)U,$$

$$(1.8) b) u(fX) = 0,$$

$$(1.8) c) u(U) = -a^2,$$

$$(1.8) d) fU = 0 \text{ and}$$

$$(1.9) g(\bar{X}, \bar{Y}) = a^2 g(X, Y) - u(X)u(Y),$$

Where,

$$X = fX \text{ and } U(X) = g(\bar{X}, U)$$

i.e. the induced structure is a general contact metric structure.

Let E and D be the Riemannian connexions in M_n and M_m respectively. Gauss and Weingarten equations are :

$$(1.10) a) E_{BX}BY = BD_XY + 'H(X, Y)N,$$

$$(1.10) b) E_{BX}N = -BHX, \text{ respectively [1].}$$

Where,

$$'H(X, Y) = g(HX, Y).$$

Let R and k denote the curvature tensors with respect to the connexions E and D respectively. The Generalised Gauss and Mainardi - Codazzi are given by [5] :

$$(1.11) a) 'R(BX, BY, BZ, BW) = 'K(X, Y, Z, W) + a^2 'H(X, Z) 'H(Y, W) -$$

$$a^2 'H(Y, Z) 'H(X, W).$$

$$(1.11) b) 'R(BX, BY, BZ, N) = a^2 \{ (D_X 'H)(Y, Z) - (D_Y 'H)(X, Z) \}.$$

$$\text{Where, } 'R(BX, BY, BZ, BW) = G(R(BX, BY, BZ), BW).$$

On the hypersurface of a hyperbolic Kahler manifold subordinate to HGF- manifold the following results hold [2] :

$$(1.12) a) (D_X f)Y = u(Y)HX - 'H(X, Y)U$$

$$(1.12) b) (D_X u)(Y) = - 'H(X, Y).$$

Agreement (1.1) in the above and in sequel λ, μ, ν, \dots will be taken as an

arbitrary vector fields in the enveloping manifold and X, Y, Z, \dots as arbitrary vector fields in the hypersurface.

Hyperbolic Almost Kahler Manifold :

Definition (2.1). Hyperbolic Hermite manifold satisfying

$$(2.1) a \quad (E \lambda \cdot F)(\mu, \nu) + (E \mu \cdot F)(\nu, \nu) + (E \nu \cdot F)(\lambda, \mu) = 0,$$

Where,

$$F(\lambda, \mu) = G(F\lambda, \mu).$$

Will be called hyperbolic almost Kahler manifold, subordinate to HGF – manifold

From the equation (1.7) a, we have

$$(2.1) b \quad G(FBX, BY) = G(BfX, BY) + u(X) G(N, BY)$$

Differentiating equation (2.1) b, covariantly w.r. to BZ, then using the equations (1.5) (1.6) (1.7) and (1.10) a, we have

$$(2.2) \quad (E_{BZ} \cdot F)(BX, BY) \text{ ob} = (D_Z \cdot f)(X, Y) + 'H(X, Z) u(Y) - 'H(Y, Z) u(X).$$

Writing two other equations by cyclic permutations of X, Y, Z we have

$$(2.3) \quad (E_{BY} \cdot F)(BZ, BX) \text{ ob} = (D_Y \cdot f)(Z, X) + 'H(Z, Y) u(X) - 'H(X, Y) u(Z)$$

and

$$(2.4) \quad (E_{BX} \cdot F)(BY, BZ) \text{ ob} = (D_X \cdot f)(Y, Z) + 'H(Y, X) u(Z) - 'H(X, Z) u(Y)$$

Thus, we have the following theorem:
Theorem (2.1). If the enveloping manifold is a hyperbolic almost Kahler manifold, its hypersurface is given by

$$(2.5) \quad (D_X \cdot f)(Y, Z) + (D_Y \cdot f)(Z, X) + (D_Z \cdot f)(X, Y) = 0$$

Proof. Adding the equations (2.2) (2.3) (2.4), we have

$$(2.6) \quad \{ (E_{BZ} \cdot F)(BX, BY) + (E_{BY} \cdot F)(BZ, BX) + (E_{BX} \cdot F)(BY, BZ) \} \text{ ob} =$$

$$(D_X \cdot f)(Y, Z) + (D_Y \cdot f)(Z, X) + (D_Z \cdot f)(X, Y)$$

Using the equation (2.1)a in the equation (2.6), we get the equation (2.5).

Corollarily (2.1). Hypersurface of Hyperbolic almost Kahler manifold is locally quasi-sasakian manifold.

Proof. Equation (2.5) Proves the statement.

Theorem (2.2). For the hypersurface of a hyperbolic almost Kahler manifold, we have

$$(2.7) \quad (D_X \cdot f)(Y, Z) + (D_Y \cdot f)(Z, X) + (D_Z \cdot f)(X, Y) + 'f((D_Z f) X - (D_X f) Z, Y)$$

$$+ 'f((D_Y f) Z - (D_Z f) Y, X) + 'f((D_X f) Y - (D_Y f) X, Z) = 0$$

Proof. We have

$$(2.8) a \quad 'f(X, Y) = g(fX, Y) = 'f(Y, X),$$

Differentiating (2.8) b covariantly w.r. to Z and Using the equation (2.8) again, we get

$$(2.9) a \quad (D_Z \cdot f)(X, Y) + 'f((D_Z f) X, Y) + 'f((X, (D_Z f) Y)) = a^2(D_Z \cdot f)(X, Y).$$

Similarly, writing two other equations, we have

$$(2.9) b \quad (D_Y \cdot f)(Z, X) + 'f((D_Y f) Z, X) + 'f((Z, (D_Y f) X)) = a^2(D_Y \cdot f)(Z, X),$$

$$(2.9) c \quad (D_X \cdot f)(Y, Z) + 'f((D_X f) Y, Z) + 'f((Y, (D_X f) Z)) = a^2(D_X \cdot f)(Y, Z),$$

Adding the Equations (2.9) a, b and c, then using the equations (2.8) a and (2.5), we get the required result.

Hypersurfaces of Flat HGF-Manifold:

Theorem (3.1) The umbilical Hypersurface of a Hyperbolic General Differentiable (HGF) manifold is of constant Riemannian curvature, if the enveloping manifold is flat.

Proof. Let the hypersurface be umbilic, i.e.

$$'H(X, Y) = g(X, Y), [1]$$

Then (1.11) a, gives

$$(3.1) \quad 'R(BX, BY, BZ, BW) \text{ ob} = 'K(X, Y, Z, W) + a^2 g(x, z)g(Y, W) - a^2 g(Y, Z)g(X, W)$$

If the enveloping manifold is flat, then (3.1) reduces to

$$(3.2) \quad 'K(X, Y, Z, W) = a^2 \{ g(Y, Z)g(X, W) - g(X, Z) g(Y, W) \}$$

This shows that the hypersurface is of constant Riemannian curvature.

Conversely, if (3.2) holds, then using (3.2) in (3.1) we have

$$'R(BX, BY, BZ, BW) = 0, \text{ that is the manifold is flat.}$$

Theorem (3.2). The scalar curvature of the umbilical hypersurface M_m of a flat HGF – manifold M_n is given by

$$(3.3) \quad r = m(m-1) a^2$$

Proof. The umbilical hypersurface is of constant Riemannian curvature (by theorem (3.1)). We have

$$K(X, Y, Z) = a^2 \{ g(Y, Z) X - g(X, Z) Y \}$$

From this we at once get the equation (3.3).

Theorem (3.3) The quasi – umbilical hypersurface of a flat HGF – manifold can never be of constant Riemannian curvature.

Proof. Let the hypersurface of a flat HGF – manifold be quasi – umbilical, then we can always write

$$(3.4) \quad 'H(X, Y) = g(X, Y) + u(X)u(Y), [1]$$

Using (3.4) in (1.11) a, we have

$$(3.5) \quad 'R(BX, BY, BZ, BW) \text{ ob} = 'K(X, Y, Z, W) + a^2 g(X, Z)g(Y, W) - a^2 g(Y, Z)g(X, W) + a^2 g(Y, W)u(X)u(Z) + a^2 g(X, Z)u(Y)u(W) - a^2 g(Y, Z)u(X)u(W) - a^2 g(X, W)u(Y)u(Z)$$

Now,

$$'K(X, Y, Z, W) = a^2 \{ g(Y, Z)g(X, W) - g(X, Z) g(Y, W) \},$$

if

$$a^2 \{ g(Y, W) u(X) u(Z) + g(X, Z)u(Y)u(W) - g(Y, Z)u(X)u(W) - g(X, W)u(Y)u(Z) \} = 0$$

Let $a^2 \neq 0$, then

$$g(Y, W)u(Z)u(X) + g(X, Z)u(Y)u(W) - g(Y, Z)u(X)u(W) - g(X, W)u(Y)u(Z) = 0$$

or

$$g(Y, W)u(X)u(Z) + u(Y)u(W)X - u(X) u(W) Y - g(X, W)u(Y)u(Z) = 0,$$

or

$$a^2 g(Y, W) + mu(Y)u(W) - u(Y)u(W) - u(Y)u(W) = 0$$

or

$$a^2 g(Y, W) + (m-2)u(Y)u(W) = 0,$$

or

$$a^2 Y + (m-2)u(Y)u(W) = 0,$$

or

$$ma^2 + (m-2)a^2 = 0, \text{ or } 2a^2(m-1) = 0 \Rightarrow a^2 = 0,$$

But $a^2 \neq 0$, thus

The quasi-umbilical hypersurface cannot be of constant Riemannian curvature.

Theorem (3.4) If the hypersurface of a flat HGF-manifold is of minimal variety,

then $\text{div}H=0$.

But the converse is not true in general.

Proof. Let the hypersurface be of minimal variety then

$\text{tr}.H = 0$, [1]

Since the enveloping manifold is flat, equation (1.11) b implies that

$$(D_X H)Y - (D_Y H)X = 0$$

Contracting this equation, we get

$$(\text{div}H) Y = Y \text{tr}.H = 0 \text{ (Since } \text{Tr}.H = 0)$$

Conversely, if $\text{div} H = 0$, then from the last equation, we get $Y \text{tr}.H = 0$ i.e. $\text{tr}.H = \text{constt.}$

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